

AMENDMENTS TO THE SPECIFICATION

Please amend paragraph [0015] of the substitute specification filed on October 19, 2004 as follows:

[0015] The process of transferring the glass substrate 4 from the heat chamber (not shown) to the process chamber 2 will be described in more detail. As described above and as illustrated in Fig. 2, the robot arm 8 moves forward in the advancing direction to position the glass substrate 4 on top of the susceptor 10. Also as noted above, the lift pins 6 are positioned to not interfere with the robot arm 8, i.e. the lift pins 6 are withdrawn inside the susceptor 10 during this time. At the step wherein the lift pins are withdrawn this time, the robot arm 8 slides the glass substrate 4 to a position wherein where the leading edge of the glass substrate 4 is 2~3 mm before a stopper pin 28. The gap between the stopper pin 28 and a point at which the glass substrate 4 begins to slide into position is 5 mm.

Please amend paragraph [0017] of the substitute specification filed on October 19, 2004 as follows:

[0017] Fig. 4A to 4D are sectional views taken along the line A-A' of Fig. 3, and represent a process whereby the glass substrate 4 is interfered with by the film-forming material which collects on the surface of the susceptor 10 due to the sliding of the glass substrate 4 on the susceptor 10 at an incline. Only a

U.S. Application No. 10/029,035

Docket No. 2658-0280P

Art Unit: 1763

Page 3 of 25

leading edge of the glass substrate 4 is shown for simplicity. Also, the arrow represents the advancing direction (see Fig. 2).